

v0.8

Param	Description	Valeur par défaut
\$0	x, step/mm	250.000
\$1	y, step/mm	250.000
\$2	z, step/mm	250.000
\$3	step pulse, usec	10
\$4	default feed, mm/min	250.000
\$5	default seek, mm/min	500.000
\$6	step port invert mask	192 (mask:11000000)
\$7	step idle delay, msec	25
\$8	acceleration, mm/sec^2	10.000
\$9	junction deviation, mm	0.050
\$10	arc, mm/segment	0.100
\$11	n-arc correction, int	25
\$12	n-decimals, int	3
\$13	report inches, bool	0
\$14	auto start, bool	1
\$15	invert step enable, bool	0
\$16	hard limits, bool	0
\$17	homing cycle, bool	0
\$18	homing dir invert mask	0 (mask:00000000)
\$19	homing feed, mm/min	25.000
\$20	homing seek, mm/min	250.000
\$21	homing debounce, msec	100
\$22	homing pull-off, mm	1.000

v0.9

Param	Description	Default value
\$0	step pulse, usec	10
\$1	step idle delay, msec	25
\$2	step port invert	0 (mask:00000000) ----- ZYX [1]
\$3	dir port invert	6 (mask:00000110) ----- ZYX [2]
\$4	step enable invert, bool	0
\$5	limit pins invert, bool	0
\$6	probe pin invert, bool	0
\$10	status report	3 (mask:00000011) [3]
\$11	junction deviation, mm	0.020
\$12	arc tolerance, mm	0.002
\$13	report inches, bool	0
\$14	auto start, bool	1
\$20	soft limits, bool	0
\$21	hard limits, bool	0
\$22	homing cycle, bool	0
\$23	homing dir invert	0 (mask:00000000) ----- ZYX [4]
\$24	homing feed, mm/min	25.000
\$25	homing seek, mm/min	500.000
\$26	homing debounce, msec	250
\$27	homing pull-off, mm	1.000
\$100	x, step/mm	250.000
\$101	y, step/mm	250.000
\$102	z, step/mm	250.000
\$110	x max rate, mm/min	500.000
\$111	y max rate, mm/min	500.000
\$112	z max rate, mm/min	500.000
\$120	x accel, mm/sec^2	10.000
\$121	y accel, mm/sec^2	10.000
\$122	z accel, mm/sec^2	10.000
\$130	x max travel, mm	200.000
\$131	y max travel, mm	200.000
\$132	z max travel, mm	200.000

v1.1

Param	Description	Default value
\$0	step pulse, user	10
\$1	step idle delay, msec	25
\$2	step port invert	0 (mask:00000000) ----- ZYX [5]
\$3	dir port invert	0 (mask:00000000) ----- ZYX [6]
\$4	step enable invert, bool	0
\$5	limit pins invert, bool	0
\$6	probe pin invert, bool	0
\$10	status report	1 (mask:00000001) [7]
\$11	junction deviation, mm	0.010
\$12	arc tolerance, mm	0.002
\$13	report inches, bool	0
\$20	soft limits, bool	0
\$21	hard limits, bool	0
\$22	homing cycle, bool	0
\$23	homing dir invert	0 (mask:00000000) ----- ZYX [8]
\$24	homing feed, mm/min	25
\$25	homing seek, mm/min	500
\$26	homing debounce, msec	250
\$27	homing pull-off, mm	1
\$30	spindle speed min RPM	1000
\$31	spindle speed max RPM	0
\$32	laser mode, boolean	0
\$100	x, step/mm	250
\$101	y, step/mm	250
\$102	z, step/mm	250
\$110	x max rate, mm/min	500
\$111	y max rate, mm/min	500
\$112	z max rate, mm/min	500
\$120	x accel, mm/sec^2	10
\$121	y accel, mm/sec^2	10
\$122	z accel, mm/sec^2	10
\$130	x max travel, mm	200
\$131	y max travel, mm	200
\$132	z max travel, mm	200